

Assignment 7

1. Apply two steps of Newton's method to find a simultaneous root of the following system of two algebraic equations starting with the approximation $x = y = 0.5$.

$$\begin{aligned}x^2 + 4y^2 - x + y - 1 &= 0 \\3x^2 + 2y^2 + x - y - 2 &= 0\end{aligned}$$

The Jacobian is the matrix with the first row being $(2x - 1, 8y + 1)$ and the second row $(6x + 1, 4y - 1)$.

In MATLAB, we can code the function and the Jacobian as follows; although you can do it by hand, too,

```
>> f = @(u)([ u(1)^2 + 4*u(2)^2 - u(1) + u(2) - 1
              3*u(1)^2 + 2*u(2)^2 + u(1) - u(2) - 2 ]);
>> J = @(u)([ 2*u(1) - 1, 8*u(2) + 1
              6*u(1) + 1, 4*u(2) - 1 ]);
>> u0 = [0.5; 0.5];
>> f(u0)
    0.25
   -0.75
```

```
>> % First iteration
>> du0 = J(u0) \ -f(u0)
    du0 =
         0.2
        -0.05
>> u1 = u0 + du0
    u1 =
         0.7
         0.45
>> f(u1) % This should be smaller
    0.05
    0.125
```

```
>> % Second iteration
>> du1 = J(u1) \ -f(u1)
    du1 =
   -0.02266949152542365
   -0.008898305084745780
>> u2 = u1 + du1
    u2 =
    0.6773305084745763
    0.4411016949152542
>> f(u2) % This should be even smaller
    ans =
    0.0008306251795462405
    0.001700077204826567
```

2. Apply one step of Newton's method to find a simultaneous root of the following system of three algebraic equations starting with the approximation $x = y = -0.5$ and $z = 1$.

$$\begin{aligned} 3x^2 + x - xy - 2y - 1 &= 0 \\ 2x + 2y^2 + xy - y + z - yz - 2 &= 0 \\ y - 2z + yz + 3z^2 &= 0 \end{aligned}$$

The Jacobian is the matrix with the first row being $(6x + 1 - y, -x - 2, 0)$, the second $(2 + y, 4y + x - 1 - z, 1 - y)$, and the third $(0, 1 + z, -2 + y + 6z)$.

Two iterations are performed for interest:

```
f = @(u)([ 3*u(1)^2 + u(1) - u(1)*u(2) - 2*u(2) - 1
          2*u(1) + 2*u(2)^2 + u(1)*u(2) - u(2) + u(3) - u(2)*u(3) - 2
          u(2) - 2*u(3) + u(2)*u(3) + 3*u(3)^2 ]);
J = @(u)([ 6*u(1) + 1 - u(2), -u(1) - 2, 0
          2 + u(2), 4*u(2) + u(1) - 1 - u(3), 1 - u(2)
          0, 1 + u(3), -2 + u(2) + 6*u(3)]);
u0 = [-0.5; -0.5; 1];
f( u0 )
0
-0.25
0

% First iteration
du0 = J(u0) \ -f(u0)
du0 =
    0.036458333333333333
   -0.036458333333333333
    0.020833333333333333

u1 = u0 + du0
u1 =
   -0.46354166666666667
   -0.53645833333333334
    1.0208333333333333e

f( u1 )
0.005316840277777901
0.002088758680555358
0.0005425347222214327

% Second iteration
du1 = J(u1) \ -f(u1)
du1 =
    0.002900757102792720
    0.001110347070392873
   -0.0007764605660071837

u2 = u1 + du1
u2 =
   -0.4606409095638740
   -0.5353479862629404
    1.020056872767326

f( u2 )
0.00002202232815706751
0.000006548729099442596
0.0000009465323174140394
```

3. Apply one step of Newton's method to find a simultaneous root of the following system of two algebraic equations starting with the approximation $x = 1$ and $y = 1.5$.

$$\begin{aligned}\sin(x) + 2 \cos(xy) &= 1 \\ \sin(xy) - 2 \cos(y) &= 1\end{aligned}$$

The Jacobian is the matrix with the first row being $(\cos(x) - 2\sin(xy)y, -2\sin(xy)x)$ and the second $(\cos(xy)y, \cos(xy)x + 2\sin(y))$.

Two iterations are performed for interest:

```
f = @(u)([ sin(u(1))          + 2*cos(u(1)*u(2)) - 1
           sin(u(1)*u(2)) - 2*cos(u(2)) - 1  ]);
J = @(u)([ cos(u(1)) - 2*sin(u(1)*u(2))*u(2), -2*sin(u(1)*u(2))*u(1)
           cos(u(1)*u(2))*u(2), cos(u(1)*u(2))*u(1) + 2*sin(u(2))  ]);
u0 = [1.0; 1.5];
f( u0 )
    -0.01705461185669765
    -0.1439794167313514

% First iteration
du0 = J(u0) \ -f(u0)
    du0 =
        -0.06643530009365024
         0.07311158482063311
u1 = u0 + du0
    u1 =
         0.9335646999063497
         1.573111584820633
f( u1 )
    0.007780124676444178
   -0.0005868419391285018

du1 = J(u1) \ -f(u1)
    du1 =
         0.003034353204493463
         0.00004766817273407990
u2 = u1 + du1
    u2 =
         0.9365990531108431
         1.573159252993367
f( u2 )
   -0.000006321773508011219
   -0.00001153324122649124
```

4. Recall the difference between Newton's method and the secant method for a single algebraic equation in a single variable. Suppose instead, you did not have the derivative. How would you generalize the secant method for two algebraic equations in two variables, or n algebraic equations in n variables? Recall that a plane is defined by three points.

As a plane is defined by three points, we could start with three initial points \mathbf{x}_0 , \mathbf{x}_1 and \mathbf{x}_2 and then for the first function, f_1 , we could find a tangent plane passing through $(\mathbf{x}_0, f_1(\mathbf{x}_0))$, $(\mathbf{x}_1, f_1(\mathbf{x}_1))$ $(\mathbf{x}_2, f_1(\mathbf{x}_2))$ and for the second function, f_2 , we could find a similar tangent plane. Recall that a plane is a function of the form $\phi(\mathbf{x}) = ax_1 + bx_2 + c$, so to pass through three points, we require that

$$ax_{0,1} + bx_{0,2} + c = f_1(\mathbf{x}_0)$$

$$ax_{1,1} + bx_{1,2} + c = f_1(\mathbf{x}_1)$$

$$ax_{2,1} + bx_{2,2} + c = f_1(\mathbf{x}_2)$$

This is a system of three equations and three unknowns, and thus, in general, has a solution, and this defines a plane. We could do this for f_2 , as well. With two secant planes, we can find a simultaneous solution or root, and hence that solution is \mathbf{x}_3 .

5. Suppose you have the ordinary differential equation $y^{(1)}(t) = \sin(y(t))$ and you know that $y(0) = 1$ and $y(0.1) = 1.086355758991046$. Use a cubic spline to approximate $y(0.05)$.

First, calculating $\delta = (0.05 - 0)/(0.1 - 0) = 0.5$.

We need to solve the system of linear equations

$$\begin{pmatrix} 0 & 0 & 0 & 1 & \dots & 1 \\ 0 & 0 & 1 & 0 & \dots & 0.1 \cdot \sin(1) \\ 1 & 1 & 1 & 1 & \dots & 1.086355758991046 \\ 3 & 2 & 1 & 0 & \dots & 0.1 \cdot \sin(1.086355758991046) \end{pmatrix}$$

Thus, we have

```
A = [0 0 0 1; 0 0 1 0; 1 1 1 1; 3 2 1 0]
```

```
A = 0      0      0      1
     0      0      1      0
     1      1      1      1
     3      2      1      0
```

```
>> b = [1 0.1*sin(1) 1.086355758991046 0.1*sin(1.086355758991046)]'
```

```
b = 1
     0.08414709848078966
     1.086355758991046
     0.08849356226254429
```

```
p = A \ b
```

```
p = -0.00007085723875786790
     0.002279517749014116
     0.08414709848078966
     1
```

```
polyval( p, 0.5 )
```

```
1.042634571522804
```

6. Suppose you knew that $y(a) = y_a$, $y(b) = y_b$, $y^{(1)}(a) = y_a^{(1)}$, $y^{(1)}(b) = y_b^{(1)}$, $y^{(2)}(a) = y_a^{(2)}$, $y^{(2)}(b) = y_b^{(2)}$. Write down the system of linear equations that would find the quintic (degree five) polynomial that satisfies these conditions.

The quintic polynomial is $p(t) = at^5 + bt^4 + ct^3 + dt^2 + et + f$, and its first and second derivatives are

$$p^{(1)}(t) = 5at^4 + 4bt^3 + 3ct^2 + 2dt + e$$

$$p^{(2)}(t) = 20at^3 + 12bt^2 + 6ct + 2d$$

Now, we scale and shift to 0 and 1 so that our algorithm can be re-used. Thus, the slopes will be modified by h and the concavities by h^2 , so we have

$$p(0) = y_a, p^{(1)}(0) = hy_a^{(1)}, p^{(2)}(0) = h^2y_a^{(2)}, p(1) = y_b, p^{(1)}(1) = hy_b^{(1)}, p^{(2)}(1) = h^2y_b^{(2)}$$

$$\begin{pmatrix} 0 & 0 & 0 & 0 & 0 & 1 & \cdots & y_a \\ 0 & 0 & 0 & 0 & 1 & 0 & \cdots & hy_a^{(1)} \\ 0 & 0 & 0 & 2 & 0 & 0 & \cdots & h^2y_a^{(2)} \\ 1 & 1 & 1 & 1 & 1 & 1 & \cdots & y_b \\ 5 & 4 & 3 & 2 & 1 & 0 & \cdots & hy_b^{(1)} \\ 20 & 12 & 6 & 2 & 0 & 0 & \cdots & h^2y_b^{(2)} \end{pmatrix}$$

7. Using Euler's method, approximate $y(1)$ with $h = 0.2$ and again with $h = 0.1$ for the initial-value problem defined by

$$y^{(1)}(t) = 2y(t) + t - 1$$

$$y(0) = 1$$

```

a = 0;
b = 1;
t0 = 0;
y0 = 1;
f = @(t, y)(2*y + t - 1);
h = 0.2;
N = 5;
ts = a:h:b;
ys = zeros( 1, N + 1 );
ys(1) = y0;
for k = 1:N
    ys(k + 1) = ys(k) + h*f(ts(k), ys(k));
end
ys
    ys = 1 1.2 1.52 2.008 2.7312 3.7837

```

```

h = 0.1;
N = 10;
tss = a:h:b;
yss = zeros( 1, N + 1 );
yss(1) = y0;
for k = 1:N
    yss(k + 1) = yss(k) + h*f(tss(k), yss(k));
end
yss
    yss = 1 1.1 1.23 1.396 1.6052 1.8662 2.1895 2.5874 3.0749 3.6698 4.3938

```

8. In Question 7, you approximated $y(0.2)$ with $h = 0.2$, and $y(0.1)$ with $h = 0.1$. The correct solutions to sixteen significant digits are $y(0.2) = 1.268868523230952$ and $y(0.1) = 1.116052068620128$. Show that the error of one step of Euler's method is $O(h^2)$ by showing that the error of your approximation at $t = 0.1$ is approximately one quarter the error at $t = 0.2$.

The approximations are 1.2 and 1.1, respectively, and thus the errors are 0.068868523230952 and 0.016052068620128, and we note that the second number is approximately one quarter the first.

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